A Pseudo-Synthetic Calibration of an Adaptive Optics System

Parker Levesque ^{1,2}, Jacob Taylor^{1,2}, Robin Swanson^{2,3} Suresh Sivanandam^{1,2}

parker.levesque@mail.utoronto.ca

(1) University of Toronto, Department of Astronomy and Astrophysics. (2) Dunlap Institute for Astronomy and Astrophysics. (3) University of Toronto, Department of Computer Science

We use a novel method to calibrate AO systems on telescopes that use convex deformable secondary mirrors, which many

existing and future large telescopes aim to include thanks to their significantly improved throughput. However, calibrating

these AO systems is challenging because an artificial light source cannot be used for this purpose and the calibration must be

done on sky. Under these constraints, we use the OOPAO simulation tool in python to model a physical system and to obtain

an ideal calibration. Current empirical methods in measuring this interaction between deformable mirror and wavefront

sensor are littered with background. Empirical calibrations together with the SPRINT technique, which seeks to extract the

misregistrations present in the physical system, will serve to properly register the simulated system as close to the physical

one as possible, thereby producing a noiseless result. This pseudo-synthetic calibration scheme has been validated on an

optical bench AO system as well as preliminary on-sky results from the MAPS project on MMT.



Extracting Parameters: The empirical calibration contains all the information about the physical system. We identify these misregistrations by using the SPRINT algorithm (1). The best-fit parameters are applied to the simulation to

create a *pseudo-synthetic* calibration of

the physical system.







Closing the Loop: The first validation of the SPRINT

algorithm on the optical bench. The total residual wavefront

error for the pseudo-synthetic calibration is remaining stable

over time when tested on synthetic atmospheric conditions.

10⁻⁵
20
40
60
80
Residual Error
Assessing Performance: We decompose the error in the correction by the contribution from each mode. The baseline for the error is set by the open loop wavefront error and the performance of the calibration is determined by how well each mode can reduce its contribution to the residual slope.

Citations: [1] SPRINT, system parameters recurrent invasive tracking: a fast and least-cost online calibration strategy for adaptive optics — CT. Heritier (2021)



